

Recall: $T: V \rightarrow W$ $\ker(T) \subseteq V$ $\text{im}(T) \subseteq W$

injective surjective

Theorem 24: $T: V \rightarrow W$ linear transformation, let $\dim(V) = \dim(W)$ be finite.

Then the following are equivalent:

(1) T is injective.

(2) T is surjective.

(3) $\dim(\text{im}(T)) = \dim(V)$.

Proof: We will prove $(1) \Leftrightarrow (3)$ and $(2) \Leftrightarrow (3)$.

(1) $\Rightarrow (3)$ T is injective. By the Rank-Nullity Theorem:

$$\dim(V) = \dim(\text{im}(T)) + \dim(\underbrace{\ker(T)}_{\text{so because } T \text{ injective}}).$$

so because T injective.

$$\dim(V) = \dim(\text{im}(T)).$$

(3) $\Rightarrow (1)$ If $\dim(V) = \dim(\text{im}(T))$ then by the Rank-Nullity Theorem

$\dim(\ker(T)) = 0$ so $\ker(T) = \{0\}$ so T is injective.

(2) $\Rightarrow (3)$ T surjective so $\text{im}(T) = W$.

$$\dim(\text{im}(T)) = \dim(W) = \dim(V).$$

(3) $\Rightarrow (2)$ T $\text{1-1} \iff \text{im}(v) = \text{im}(w) \iff v = w$

$(\exists) \rightarrow (\exists)$ If $\dim(V) = \dim(\text{im}(T))$ then:

$$\dim(W) = \dim(V) = \dim(\text{im}(T)) \quad \text{we have } \text{im}(T) \subseteq W$$

so $\text{im}(T) = W$ so T surjective. \square .

Remark: We should often consider computing dimensions of $\ker(T)$ and $\text{im}(T)$ instead of the dimensions of V and W .

Remark: When checking anything about a linear transformation $T: V \rightarrow W$, it is enough to do so on a basis of V .

Example: $T: \underbrace{\mathbb{R}_2[x]}_{P_2(\mathbb{R})} \longrightarrow \underbrace{\mathbb{R}_3[x]}_{P_3(\mathbb{R})}$, check if T is injective or surjective.
 $f(x) \mapsto 2f'(x) + \int_0^x 3f(x) dx$

Method: compute $\dim(\ker(T))$ and $\dim(\text{im}(T))$.

$$\mathbb{R}_2[x] = \text{Span} \left\{ \underbrace{1, x, x^2}_{\text{basis}} \right\} \quad T(1) = 3x \quad T(x) = 2 + \frac{3x^2}{2} \quad T(x^2) = 4x + x^3$$

$$\text{So } \text{im}(T) = \text{Span} \left\{ 3x, 2 + \frac{3x^2}{2}, 4x + x^3 \right\} \quad \text{so } \dim(\text{im}(T)) = 3. \quad \underbrace{\text{linearly independent}}$$

Since $\mathbb{R}_3[x]$ has dimension 4, T is not surjective.

By Rank-Nullity Theorem:

$$\underbrace{\dim(\mathbb{R}_2[x])}_{3} = \dim(\ker(T)) + \underbrace{\dim(\text{im}(T))}_{3} \quad \text{so } \dim(\ker(T)) = 0.$$

So T is injective.

Theorem 25: $T: V \rightarrow W$, let $\{v_1, \dots, v_n\}$ be a basis of V , let $\{w_1, \dots, w_m\}$ be a basis of W . Suppose that $T(v_i) = w_i$ for all $i=1, \dots, n$. Then T is unique.

Proof: Let $T': V \rightarrow W$ be a linear transformation such that $T'(v_i) = w_i$ for all $i=1, \dots, n$. We want to prove $T = T'$.

Recall that two functions are the same when they send the same element in the source to the same element in the image.

Pick $v \in V$, since $\{v_1, \dots, v_n\}$ is a basis of V , write $v = \sum_{i=1}^n a_i \cdot v_i$.

$$\begin{aligned} \text{Now: } T(v) &= T\left(\sum_{i=1}^n a_i \cdot v_i\right) = \sum_{i=1}^n a_i \cdot \underbrace{T(v_i)}_{w_i} = \sum_{i=1}^n a_i \cdot w_i = \\ &= \sum_{i=1}^n a_i \cdot \underbrace{T'(v_i)}_{w_i} = T'\left(\sum_{i=1}^n a_i \cdot v_i\right) = T'(v). \end{aligned}$$

So $T = T'$.

$$T(v_i) = T'(v_i)$$

□.

$$v = \sum_{i=1}^n a_i \cdot v_i.$$

Definition: Let V be a vector space with basis $\{v_1, \dots, v_n\}$. Suppose that $v \in V$ is

expressed as $v = \sum_{i=1}^n a_i \cdot v_i$. We say that a_1, \dots, a_n are the coordinates

of v with respect to β . The coordinate vector of v with respect to β is:

$$[v]_{\beta} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$$

$$\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \neq \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}_{\beta}$$

Example: $\mathbb{R}_2[x]$ $P_1 = \{1, x, x^2\}$ $P_2 = \{1+x, 1-x, 3x^2\}$

$$p(x) = 3 - 2x + 4x^2 \quad [p(x)]_{P_1} = \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} \quad [p(x)]_{P_2} = \begin{bmatrix} 1/2 \\ 5/2 \\ 4/3 \end{bmatrix}.$$

$$p(x) = \frac{1}{2}(1+x) + \frac{5}{2}(1-x) + \frac{4}{3}3x^2$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = 1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 2 \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 3 \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + 4 \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$S = \{e_1, e_2, e_3, e_4\}$$