

Recall: We saw that we could "compose / concatenate" linear transformations. Specifically, make this formal algebraically.

we saw a rotation with a scaling.

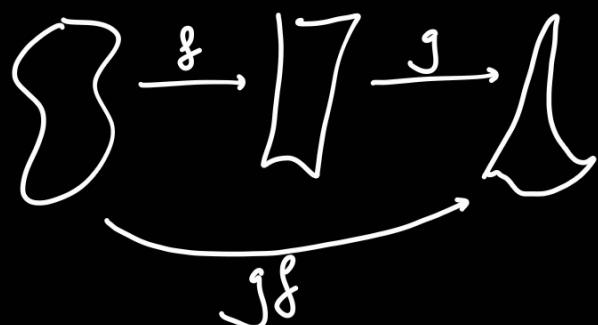
let T be a linear transformation given by $\begin{bmatrix} 6 & 7 \\ 8 & 9 \end{bmatrix}$, let S be a linear transformation

given by $\begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}$. We want to find $\vec{z} = T(S(\vec{x}))$. We do this in two steps:

\uparrow
first S
 \downarrow
then T

$\vec{y} = S(\vec{x})$, then $\vec{z} = T(\vec{y})$. Looking at the equations given by these equalities:

$$\begin{aligned} y_1 &= x_1 + 2x_2 & \text{and} & \quad z_1 = 6y_1 + 7y_2 & \text{so} & \quad z_1 = 27x_1 + 47x_2 \\ y_2 &= 3x_1 + 5x_2 & & z_2 = 8y_1 + 9y_2 & & z_2 = 35x_1 + 61x_2 \\ \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} &= \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} & \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} &= \begin{bmatrix} 6 & 7 \\ 8 & 9 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} & \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} &= \begin{bmatrix} 27 & 47 \\ 35 & 61 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ S & & T & & TS & \end{aligned}$$



This computation should mean that $\vec{z} = TS(\vec{x})$ is given by $\begin{bmatrix} 27 & 47 \\ 35 & 61 \end{bmatrix}$, and this should

be the product of the matrices giving T and S , namely $\begin{bmatrix} 6 & 7 \\ 8 & 9 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix}$.

Matrix multiplication:

Let B be an $n \times p$ matrix, let A be an $q \times n$. If (and only if) $p=q$ then

column
 \swarrow

\nwarrow
row

the product BA is the matrix associated to the linear transformation

$T(\vec{x}) = B(A\vec{x})$. This product BA is an $n \times n$ matrix.

$$\begin{array}{ccc} \vec{x} & & A\vec{x} \\ \mathbb{R}^m & \xrightarrow{A} & \mathbb{R}^p \\ & & \mathbb{R}^p \xrightarrow{B} \mathbb{R}^n \end{array}$$

Theorem: Let B be an $n \times p$ matrix and A a $p \times m$ matrix. Then:

$$(i) BA = B \begin{bmatrix} | & | & | \\ \vec{v}_1 & \dots & \vec{v}_m \\ | & & | \end{bmatrix} = \begin{bmatrix} | & | & | \\ B\vec{v}_1 & \dots & B\vec{v}_m \\ | & & | \end{bmatrix}.$$

$$(ii) C = BA = \begin{bmatrix} | & | & | \\ -\vec{w}_1 & - & - \\ \vdots & & \vdots \\ -\vec{w}_n & - & - \end{bmatrix} \begin{bmatrix} | & | & | \\ \vec{v}_1 & \dots & \vec{v}_m \\ | & & | \end{bmatrix} \text{ has entries } c_{ij} = \vec{w}_i \cdot \vec{v}_j = \sum_{k=1}^p b_{ik} a_{kj}.$$

Example: Matrix multiplication is not commutative:

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 3 & 7 \end{bmatrix} \neq \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 4 & 6 \\ 3 & 4 \end{bmatrix}$$

Algebraic rules:

$$(i) \text{ If } A \text{ is an } n \times n \text{ matrix : } A \cdot I_m = A = I_n \cdot A \quad \text{identity matrix } n \times n$$

$$(ii) \text{ Matrix multiplication is associative : } (AB)C = A(BC)$$

(iii) Matrix multiplication distributes over addition:

$$\underbrace{(A+B)}_{1st} C = \underbrace{(AC)}_{1st} + \underbrace{(BC)}_{1st} \quad \text{and} \quad A'(B'+C') = A'B' + A'C'$$

(iv) Multiplication by scalars can be factored out:

$$(k\Delta)B = k(\Delta B) = \Delta(kB).$$