

Question: What is the determinant of an orthogonal matrix?

$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ has determinant -1 . Answer: ± 1

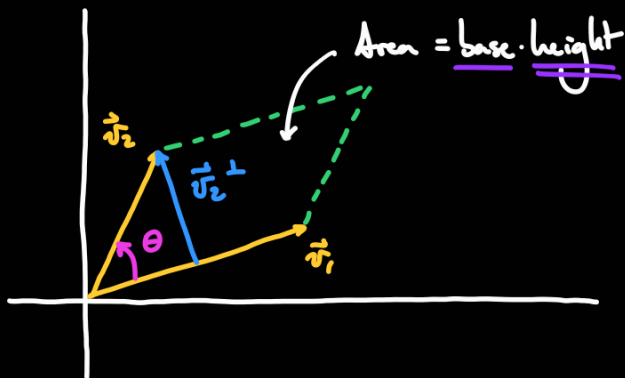
$A^T A = I_n \longrightarrow \det(A^T A) = \det(I_n) \longrightarrow \overbrace{\det(A^T) \det(A)}^{\det(A) \text{ by symmetry of det}} = 1$

$\longrightarrow \det(A) \det(A) = 1 \longrightarrow (\det(A))^2 = 1.$

so $\det(A) = \pm 1.$

Geometric interpretation of the determinant:

$A = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 \end{bmatrix}$ is a 2×2 matrix, then $\det(A) = \|\vec{v}_1\| \cdot \|\vec{v}_2\| \cdot \sin(\theta)$ where θ is the angle between \vec{v}_1 and \vec{v}_2 .



$\|\vec{v}_2^\perp\| = \|\vec{v}_2\| \cdot \sin(\theta)$

$|\det(A)| = \|\vec{v}_1\| \cdot \|\vec{v}_2^\perp\| = \text{Area}$

$|\det(A)|$ is the area of the parallelogram spanned by \vec{v}_1 and \vec{v}_2 .

$A = \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_n \end{bmatrix}$ is an $n \times n$ matrix, invertible, so by Gram-Schmidt A has a QR

decomposition: $A = \underbrace{Q}_{\text{orthogonal}} \underbrace{R}_{\text{upper triangular with positive entries in the diagonal}}$

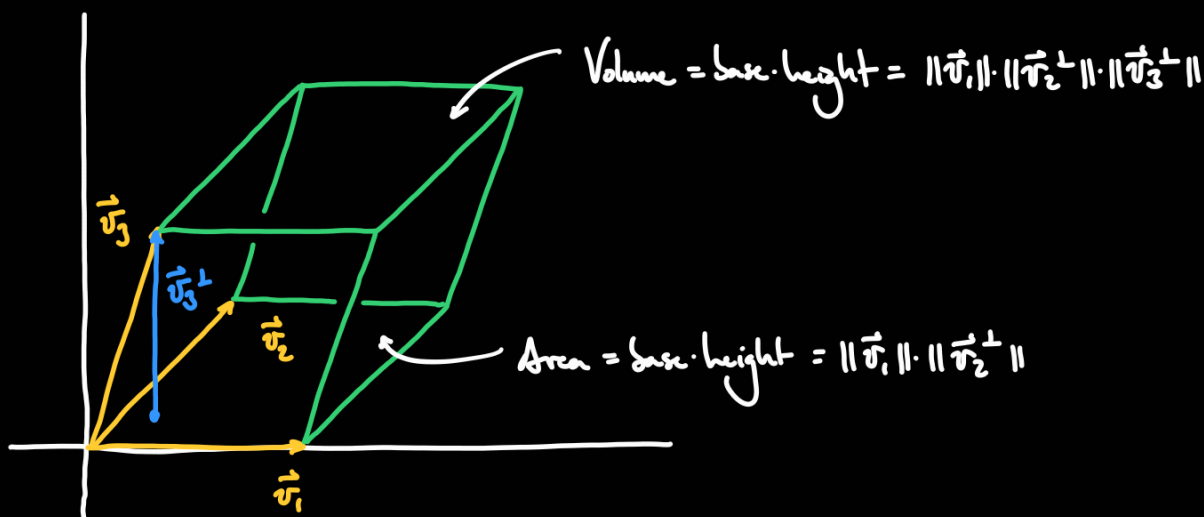
$|\det(A)| = |\det(QR)| = |\det(Q)| \cdot |\det(R)| = c_{11} \cdot c_{22} \cdot \dots \cdot c_{nn} = \underbrace{\|\vec{v}_1\| \cdot \|\vec{v}_2^\perp\| \cdot \dots \cdot \|\vec{v}_n^\perp\|}_{\text{Area}}$

$$r_{11} = \|\vec{v}_1\|, r_{22} = \|\vec{v}_2^\perp\|, \dots, r_{nn} = \|\vec{v}_n^\perp\|$$

Generalizes the formula:
Area = base · height.

\vec{v}_i^\perp is the component of \vec{v}_i perpendicular to $\text{span}(\vec{v}_1, \dots, \vec{v}_{i-1})$.

Case $n=3$:



The volume in \mathbb{R}^n of the linearly independent vectors $\vec{v}_1, \dots, \vec{v}_n$ is $\det \begin{bmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_n \\ | & & | \end{bmatrix}$.

We can also use determinants to find solutions of linear systems:

Theorem: (Cramer's rule) Let $A\vec{x} = \vec{b}$, if A is an invertible $n \times n$ matrix then

the solution has i -th component:

$$x_i = \frac{\det(A_{\vec{b}, i})}{\det(A)}$$

where $A_{\vec{b}, i}$ is the matrix obtained when we replace the i -th column of A by \vec{b} .

The classical adjoint of an invertible matrix A , denoted $\text{adj}(A)$, is the matrix:

$$(\text{adj}(A))_{ij} = (-1)^{i+j} \cdot \det(A_{ji})$$

Theorem: $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$

Example: $A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 2 & 1 & 2 \end{bmatrix}$, to compute A^{-1} we first compute all minors $\det(A_{ij})$

and put them in their respective positions in a 3×3 matrix:

$$\begin{bmatrix} \overset{+}{(-1)^{1+1}} \det(A_{11}) & \overset{-}{(-1)^{1+2}} \det(A_{12}) & \overset{+}{(-1)^{1+3}} \det(A_{13}) \\ \overset{-}{(-1)^{2+1}} \det(A_{21}) & \overset{+}{(-1)^{2+2}} \det(A_{22}) & \overset{-}{(-1)^{2+3}} \det(A_{23}) \\ \overset{+}{(-1)^{3+1}} \det(A_{31}) & \overset{-}{(-1)^{3+2}} \det(A_{32}) & \overset{+}{(-1)^{3+3}} \det(A_{33}) \end{bmatrix} = \begin{bmatrix} 3 & -4 & -1 \\ -1 & -4 & 3 \\ -4 & 8 & -4 \end{bmatrix}$$

now we take the transpose:

$$\begin{bmatrix} 3 & -1 & -4 \\ -4 & -4 & 8 \\ -1 & 3 & -4 \end{bmatrix} = \text{adj}(A)$$

finally, we divide by $\det(A) = -8$:

$$A^{-1} = \frac{\text{adj}(A)}{\det(A)} = \begin{bmatrix} -3/8 & 1/8 & 1/8 \\ 1/8 & 1/8 & -1 \\ 1/8 & -3/8 & 1/8 \end{bmatrix}$$

$$\det \begin{bmatrix} | & | & | \\ \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \\ | & | & | \end{bmatrix} = \vec{v}_1 \cdot (\vec{v}_2 \times \vec{v}_3)$$

$$\|\vec{v}_2 \times \vec{v}_3\| = \|\vec{v}_2^\perp\| \cdot \|\vec{v}_3^\perp\|$$

\uparrow \uparrow
 $\text{span}(\vec{v}_1)$ $\text{span}(\vec{v}_1, \vec{v}_2)$