

Problem 5.3.35:

Find an orthogonal transformation  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  such that  $T \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$$T = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \vec{u}_1 = T(\vec{e}_1), \quad \vec{u}_2 = T(\vec{e}_2), \quad \vec{u}_3 = T(\vec{e}_3)$$

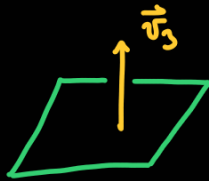
Orthogonal transformations always have inverses, and they are computed via transposing.

$$T^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = T^{-1} T \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} \quad \text{so } T^{-1}(\vec{e}_3) = \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix}.$$

If we find two additional vectors that are orthogonal and orthogonal to  $\begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix}$  and have length one, we are done.

$$T = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad T \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$T^{-1} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix}$$



$$\frac{2}{3}x + \frac{2}{3}y + \frac{1}{3}z = 0 \quad 2x + 2y + z = 0$$

$$2 \cdot \frac{-2}{3} + 2 \cdot \frac{1}{3} + \frac{2}{3} = 0$$

$$\vec{v}_1 = \begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \end{bmatrix}$$

$$\vec{v}_3 \cdot \vec{v}_1 = \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} \cdot \begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \end{bmatrix} = \frac{2}{3} \cdot \frac{-2}{3} + \frac{2}{3} \cdot \frac{1}{3} + \frac{1}{3} \cdot \frac{2}{3} = 0$$

Using that  $\vec{v}_2$  has to be perpendicular to  $\vec{v}_1$  and  $\vec{v}_3$ , and in  $V$ , we can find:

$$\vec{v}_2 = \begin{bmatrix} -1/3 \\ 2/3 \\ -2/3 \end{bmatrix} \quad (\text{or compute the cross product})$$

Now:

$$T^{-1} = \begin{bmatrix} -2/3 & -1/3 & 2/3 \\ 1/3 & 2/3 & 2/3 \\ 2/3 & -2/3 & 1/3 \end{bmatrix}, \text{ and taking inverses and transposes of orthogonal}$$

matrices is the same thing, so:

$$T = \begin{bmatrix} -2/3 & 1/3 & 2/3 \\ -1/3 & 2/3 & -2/3 \\ 2/3 & 2/3 & 1/3 \end{bmatrix}$$

orthogonal matrices: square matrices whose columns form an orthonormal basis.

$$\begin{vmatrix} i & j & k \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = i \cdot 0 - j \cdot 0 + k \cdot 1 = k \cdot 1$$

We want  $\begin{bmatrix} i & j & k \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$  to have non-zero determinant.

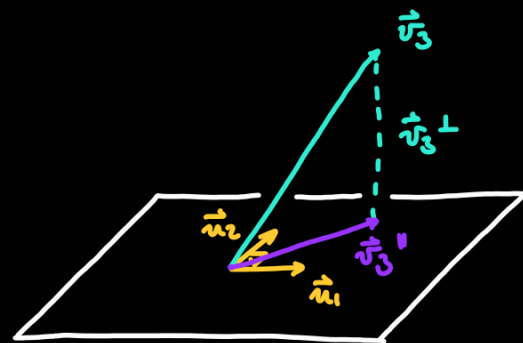
$x \quad y \quad z$

Problem 5.2.13.:

Gram-Schmidt:  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$

$\vec{v}_3$

$$\vec{u}_1 = \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \end{bmatrix}, \quad \vec{u}_2 = \begin{bmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{bmatrix}$$

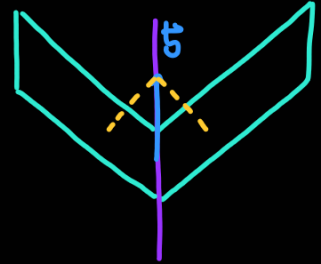


$$\begin{aligned} \vec{v}_3'' &= (\vec{v}_3 \cdot \vec{u}_1) \vec{u}_1 + (\vec{v}_3 \cdot \vec{u}_2) \vec{u}_2 = \left(\frac{2}{2} + \frac{1}{2} - \frac{1}{2}\right) \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{bmatrix} + \left(\frac{-2}{2} - \frac{1}{2} - \frac{1}{2}\right) \begin{bmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 1/2 \end{bmatrix} = \\ &= \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 3/2 \\ 3/2 \\ -1/2 \end{bmatrix} \end{aligned}$$

$$\vec{v}_3^\perp = \vec{v}_3 - \vec{v}_3^\parallel = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \end{bmatrix} - \begin{bmatrix} -1/2 \\ 3/2 \\ 3/2 \\ -1/2 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix}, \quad \|\vec{v}_3^\perp\| = \sqrt{\frac{1}{4} + \frac{1}{4} + \frac{1}{4} + \frac{1}{4}} = 1$$

$$\vec{u}_3 = \frac{\vec{v}_3^\perp}{\|\vec{v}_3^\perp\|} = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix}$$

Theorem 5.4.7:  $A\vec{x} = \vec{b}$   $A$   $n \times m$



Recall: If  $\ker(A) = \{0\}$  then  $\vec{x}^* = (A^T A)^{-1} A^T \vec{b}$ .

Why? Because if  $\ker(A) = \{0\}$  then  $A^T A$  is invertible, so the normal

equation  $A^T A \vec{x} = A^T \vec{b}$  has unique solution  $\vec{x} = (A^T A)^{-1} A^T \vec{b}$ .

Also, finding  $\vec{x}^*$  is finding the projection of  $\vec{b}$  onto  $\text{im}(A)$ . How?

Well,  $\text{proj}_{\text{im}(A)}(\vec{b}) = A\vec{x}^*$ .

Then:  $\text{proj}_V(\vec{b}) = A(A^T A)^{-1} A^T \vec{b}$ .

$$\text{proj}_V : \mathbb{R}^m \longrightarrow \mathbb{R}^m \\ \vec{b} \longmapsto A(A^T A)^{-1} A^T \vec{b}$$

(as long as  $\ker(A) = \{0\}$ )

Why is  $\vec{x} = (A^T A)^{-1} A^T \vec{b}$  a least-squares solution of  $A\vec{x} = \vec{b}$ ?

Why is a solution of  $A^T A \vec{x} = A^T \vec{b}$  a least-squares solution of  $A\vec{x} = \vec{b}$ ?

$$A^T A \vec{x}^* = A^T \vec{b} \iff A^T \vec{b} - A^T A \vec{x}^* = \vec{0} \iff A^T (\vec{b} - A \vec{x}^*) = \vec{0}$$

$$\iff \vec{b} - A \vec{x}^* \text{ is in } \ker(A^T) = (\text{im}(A))^\perp \iff A \vec{x}^* = \text{proj}_{\text{im}(A)} \vec{b}$$

clear conceptually, harder

Pythagoras Theorem

mathematically rigorously

Decompose:

$$\longleftrightarrow \| \vec{b} - A\vec{x}^* \| \leq \| \vec{b} - A\vec{x} \| \text{ for all } \vec{x} \text{ in } \mathbb{R}^m$$

$$\underbrace{\vec{b} - A\vec{x}^*}_{\text{in}(A)^\perp} = \underbrace{\vec{b}''}_{\text{in}(A)^\perp} + \underbrace{\vec{b}' - A\vec{x}^*}_{\text{in}(A)} \text{ must be } \vec{0}$$

$$\longleftrightarrow \vec{x}^* \text{ is a least-squares solution of } A\vec{x} = \vec{b}.$$

Why do we need  $\text{ker}(A) = \{\vec{0}\}$ ?

Note that  $\text{ker}(A) = \text{ker}(A^T A)$ :

1. If  $\vec{v}$  in  $\text{ker}(A)$  then  $A^T A\vec{v} = A^T(A\vec{v}) = A^T \vec{0} = \vec{0}$  so  $\vec{v}$  is in  $\text{ker}(A^T A)$ .

2. If  $\vec{v}$  in  $\text{ker}(A^T A)$  then  $A^T A\vec{v} = \vec{0}$ . Since  $A\vec{v}$  is in  $\text{im}(A)$  and  $\text{ker}(A^T)$  because  $A^T(A\vec{v}) = \vec{0}$ , then:

$$A\vec{v} \text{ is in } \text{im}(A) \text{ and } (\text{im}(A))^\perp, \text{ so } A\vec{v} = \vec{0}.$$

So  $\vec{v}$  is in  $\text{ker}(A)$ .

If  $\text{ker}(A) = \{\vec{0}\}$  then  $\text{ker}(A^T A) = \{\vec{0}\}$ , but  $A^T A$  is a square matrix. So

$A^T A$  is invertible.

$$P = Q Q^T, \text{ why is } P \text{ symmetric? } P^T = P$$

$$P^T = (Q Q^T)^T = (Q^T)^T Q^T = Q Q^T = P$$