

2. Subspaces of \mathbb{R}^n

$\hookrightarrow \text{im}(\tau)$ lies here

$$\tau: \Sigma \rightarrow \Sigma$$

The image of a linear transformation τ is set of values of the function.

$$\text{im}(\tau) = \left\{ \tau(x) \mid x \in \Sigma \right\} = \left\{ y \in \Sigma \mid y = \tau(x) \text{ for some } x \in \Sigma \right\}$$

such that
in, "belongs to"
curly bracket

Example:

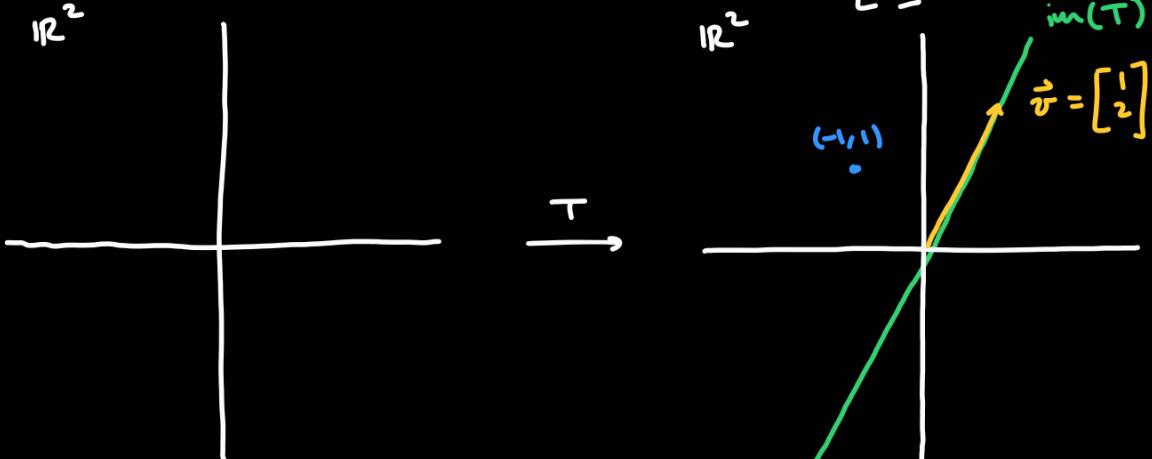
1. $\tau: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $\begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$. To find the image, we apply τ to \vec{x} :

source target

$$\tau(\vec{x}) = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ 6 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3x_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} =$$

$$= (x_1 + 3x_2) \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

So $\text{im}(\tau)$ is scalar multiples of $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$: $\text{im}(\tau) = \left\{ k \begin{bmatrix} 1 \\ 2 \end{bmatrix} \mid k \in \mathbb{R} \right\}$.



As invertible. pick $\vec{y} \in \mathbb{R}^2$

then we want $\vec{x} \in \mathbb{R}^2$ with
source

$$A\vec{x} = \vec{y}.$$

$$\vec{x} = A^{-1}\vec{y}.$$

$$\text{im}(A) = \mathbb{R}^2$$

$(-1, 1)$ is in \mathbb{R}^2

$(-1, 1)$ is not in $\text{im}(\tau)$

$$\tau: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad \text{im}(\tau) = \begin{cases} \text{one line} \\ \text{through } \vec{o} \end{cases}$$

"subspaces of \mathbb{R}^n "

Theorem: Let $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ be a linear transformation. Then:

⊗

$$(i) \vec{0} \in \text{im}(T), \quad \vec{0} \in \mathbb{R}^n.$$

\mathbb{R}^n

\mathbb{R}^{n-1}

⋮

\mathbb{R}^2

$$(ii) \text{ If } \vec{v}_1, \vec{v}_2 \in \text{im}(T) \text{ then } \vec{v}_1 + \vec{v}_2 \in \text{im}(T).$$

\mathbb{R}^1

$$(iii) \text{ If } \vec{v} \in \text{im}(T) \text{ then } k\vec{v} \in \text{im}(T) \text{ for any } k \in \mathbb{R}.$$

$\mathbb{R}^0 = \{\vec{0}\}$

These properties will later define "subspaces".

Let $\vec{v}_1, \dots, \vec{v}_m$ be vectors in \mathbb{R}^n . The set of all their linear combinations is called

their span: $\text{span}(\vec{v}_1, \dots, \vec{v}_m) = \{ c_1\vec{v}_1 + \dots + c_m\vec{v}_m \mid c_1, \dots, c_m \in \mathbb{R} \}$

The image of a linear transformation is the span of its columns.

$T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ $\underbrace{\begin{bmatrix} | & | & | \\ \vec{v}_1 & \dots & \vec{v}_m \\ | & & | \end{bmatrix}}_T, \text{ then } \text{im}(T) = \text{span}(\vec{v}_1, \dots, \vec{v}_m).$

The kernel of $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is the set of values that the function sends to $\vec{0}$.

$\text{ker}(T) = \{ \vec{x} \in \mathbb{R}^m \mid T(\vec{x}) = \vec{0} \}$, the solutions of the equation $T(\vec{x}) = \vec{0}$.

Example: Find the kernel of $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix}$.

We need to solve $T(\vec{x}) = \vec{0}$. This is:

$$\begin{array}{l} x_1 + x_2 + x_3 = 0 \\ x_1 + 2x_2 + 3x_3 = 0 \end{array} \sim \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & 3 & 0 \end{array} \right] \xrightarrow{\text{reduce}} \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \end{array} \right]$$

$$x_1 = x_3, \quad x_2 = -2x_3.$$

Set $x_1 = t$ the free variable, then:

$$\vec{x} = \begin{bmatrix} t \\ -2t \\ t \end{bmatrix} = t \cdot \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \text{ so } \ker(T) = \left\{ k \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \mid k \in \mathbb{R} \right\}.$$

Example: T invertible linear transformation. If $\vec{x} \in \ker(T)$ then $T(\vec{x}) = \vec{0}$, so
 \downarrow associated matrix

$$A\vec{x} = \vec{0}. \text{ Applying } A^{-1}: \vec{0} = A^{-1}\vec{0} = A^{-1}(A\vec{x}) = \vec{x}. \text{ So } \ker(T) = \{\vec{0}\} = \emptyset.$$

Example: A $n \times m$ matrix with $\ker(A) = \emptyset$. Then the system $A\vec{x} = \vec{0}$ has
exactly one solution. \downarrow because the kernel of A has one single element.
Thus, there are no free variables. Thus all my variables

are leading. Thus $\text{rank}(A) = m$.

A $n \times m$ $n \rightsquigarrow$ equations
 $m \rightsquigarrow$ variables

$n \times n$ matrix with rank n
is invertible.

Note: The previous theorem $\textcircled{2}$ is true if we replace image by kernel.

Theorem: A $n \times m$ matrix

Notation: $\{\vec{0}\} = \emptyset$.

(i) $\ker(A) = \emptyset$ iff $\text{rank}(A) = m$.

(ii) If $\ker(A) = \emptyset$ then $m \leq n$.

(iii) If $m > n$ then there are non-zero vectors in $\ker(A)$

(iv) Let $n = m$. $\ker(A) = \emptyset$ iff A is invertible.

Linear combination: v_1, \dots, v_m pick some scalars c_1, \dots, c_m ,

multiply $c_1 \vec{v}_1, c_2 \vec{v}_2, \dots, c_m \vec{v}_m$, then add them up:

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_m \vec{v}_m.$$