

6. Symmetric matrices and quadratic forms.

We were interested in finding eigenbasis.

We say that a matrix is diagonalizable when it has an eigenbasis.

We are now interested in finding orthonormal eigenbasis.

We say that a matrix is orthogonally diagonalizable if it has an orthonormal eigenbasis.

$$A = S \Lambda S^{-1} = S \Lambda S^T$$

↑
if $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$ with $S = \begin{bmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_n \\ | & & | \end{bmatrix}$, then S is orthogonal
is orthonormal $S^{-1} = S^T$

Theorem: (Spectral Theorem) A matrix is orthogonally diagonalizable if and only if it is symmetric.

Remark: \Rightarrow If A is orthogonally diagonalizable then A is symmetric.
 $A = S \Lambda S^T$, Λ diagonal $A = A^T$

$$A^T = (A)^T = (S \Lambda S^T)^T = (S^T)^T \Lambda^T S^T = S \Lambda S^T = A.$$

Question: Why does orthogonality preserve eigenspaces?

Answer: Having different eigenvalues implies orthogonality.

Π associated to A is a symmetric matrix \Rightarrow $\vec{v}_1, \dots, \vec{v}_n$ are orthogonal

Theorem: Let A be a symmetric matrix, v_1 and v_2 eigenvectors with distinct

eigenvalues λ_1 and λ_2 . Then $v_1 \cdot v_2 = 0$, namely v_1 and v_2 are orthogonal. In particular, they are linearly independent.

Recall: Eigenvectors with different eigenvalues are linearly independent.

Proof: $A = A^T$, $v_1 \cdot Av_1 = \lambda_1 v_1$, $v_2 \cdot Av_2 = \lambda_2 v_2$.

We want $v_1 \cdot v_2 = 0$.

$$v_1 \cdot v_2 = \|v_1\| \cdot \|v_2\| \cdot \cos(\theta)$$

$$v_1 = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \quad v_2 = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} \quad v_1 \cdot v_2 = a_1 b_1 + \dots + a_n b_n$$

$$v_1 \cdot v_2 = \begin{bmatrix} a_1 & \dots & a_n \end{bmatrix} \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = v_1^T v_2$$

$$v_1^T A v_2$$

$$(a) \quad v_1^T (A v_2) = v_1^T (\lambda_2 v_2) = \lambda_2 v_1^T v_2$$

$$(b) \quad (v_1^T A) v_2 = (v_1^T A^T) v_2 = (A v_1)^T v_2 = (\lambda_1 v_1)^T v_2 = \lambda_1 v_1^T v_2$$

So:

$$\lambda_2 v_1^T v_2 = v_1^T A v_2 = \lambda_1 v_1^T v_2 \implies \lambda_2 v_1^T v_2 - \lambda_1 v_1^T v_2 = 0$$

$$\implies \underbrace{(\lambda_2 - \lambda_1)}_{\text{distinct}} v_1^T v_2 = 0 \implies v_1^T v_2 = 0 \quad \text{so } v_1 \cdot v_2 = 0. \quad \square$$

Method for computing orthonormal eigenbasis:

1. Find the eigenvectors and eigenspaces.

2. Find a basis of each eigenspace. Use Gram-Schmidt to find an orthonormal eigenbasis for each eigenspace.

3. Concatenate these eigenbases.

Example: Find an orthonormal eigenbasis for $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$.

$$\lambda = 2 \quad \lambda = 0$$

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\vec{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \vec{u}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

1. They are orthogonal. (linear independent)

2. They have length one.

3. They are eigenvectors.

Example: Find an orthonormal eigenbasis of $A = \begin{bmatrix} 2/3 & 1/3 & -1/3 \\ 1/3 & 2/3 & 1/3 \\ -1/3 & 1/3 & 2/3 \end{bmatrix}$.

$$\lambda = 1 \quad \lambda = 0$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

\vec{v}_1 \vec{v}_2

$$\vec{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \vec{u}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix} \quad \vec{u}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

\vec{v}_2^\perp \rightarrow \vec{v}_1^\perp \rightarrow \vec{v}_3^\perp \rightarrow \vec{v}_1

$$u_2 = \frac{\vec{v}_2^\perp}{\|\vec{v}_2^\perp\|}, \quad \vec{v}_2^\perp = \text{proj}_{\text{span}(\vec{u}_1)}(\vec{v}_2) = (\vec{v}_2 \cdot \vec{u}_1) \vec{u}_1 = \dots = \frac{1}{2} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\vec{v}_2^\perp = \vec{v}_2 - \vec{v}_2^\parallel = \begin{bmatrix} -1/2 \\ 1/2 \\ 1 \end{bmatrix}$$