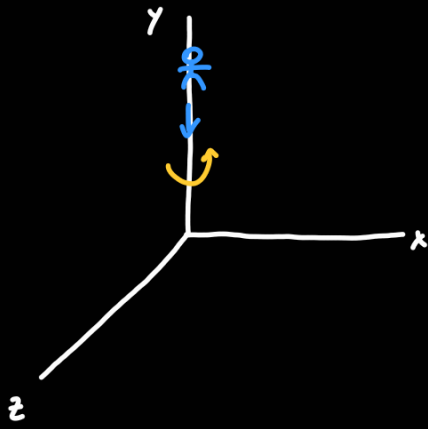


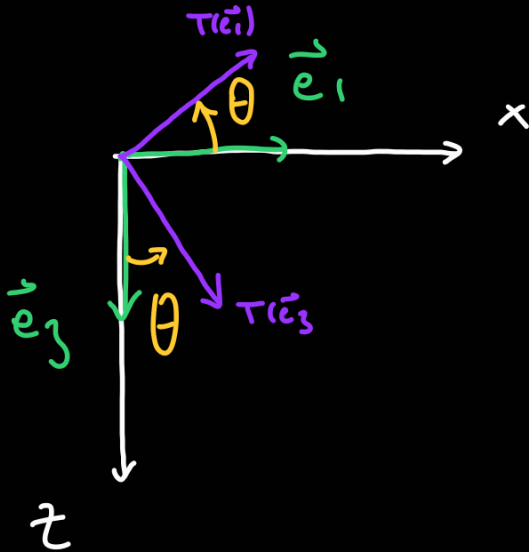
Midterm 1 Problem 4:



$$T(\vec{e}_1) = \begin{bmatrix} \cos(\theta) \\ 0 \\ -\sin(\theta) \end{bmatrix}$$

$$T(\vec{e}_2) = \vec{e}_2$$

$$T(\vec{e}_3) = \begin{bmatrix} \sin(\theta) \\ 0 \\ \cos(\theta) \end{bmatrix}$$



Problem 3.3.28:

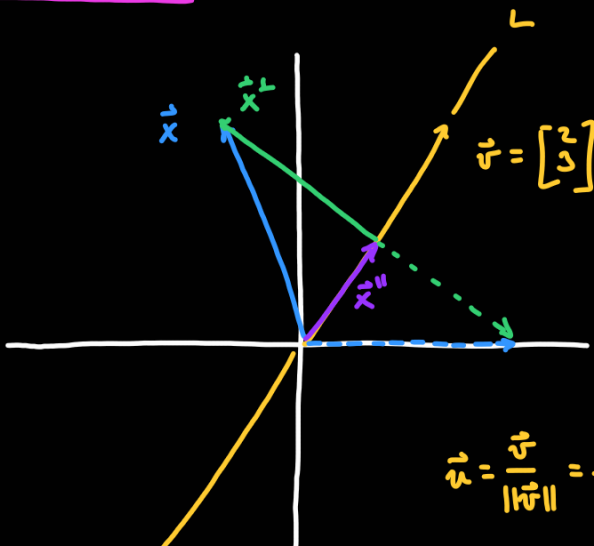
$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 4 \\ 2 & 3 & 4 & k \end{bmatrix} \xrightarrow{\substack{R_4 - 2R_1 \\ R_4 - 3R_2 \\ R_4 - 4R_3}} \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & k-29 \end{bmatrix} \xrightarrow{\substack{R_4 \\ k-29}}$$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$\text{ref}(A) = I_4$

$k \neq 29$

Problem 3.4.38: Matrix of reflection about $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$.



$$T(\vec{x}) = \vec{x} - 2\vec{x}^\perp = \vec{x}'' - \vec{x}^\perp$$

$$T(\vec{e}_1) = \vec{e}_1 - 2 \cdot \frac{1}{13} \begin{bmatrix} 9 \\ -6 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} -5 \\ 12 \end{bmatrix}$$

$$\vec{e}_1 = \vec{e}_1'' + \vec{e}_1^\perp$$

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\sqrt{13}} \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\vec{x}'' = \text{proj}_L(\vec{x}) = (\vec{x} \cdot \vec{u}) \cdot \vec{u} =$$

$$= \frac{2}{\sqrt{13}} \cdot \frac{1}{\sqrt{13}} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 4 \\ 6 \end{bmatrix}$$

$$\vec{e}_1^\perp = \begin{bmatrix} 1 \\ 0 \end{bmatrix} - \frac{1}{13} \begin{bmatrix} 4 \\ 6 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 9 \\ -6 \end{bmatrix}$$

$$T(\vec{e}_2) = \vec{e}_2 - 2 \cdot \frac{1}{13} \begin{bmatrix} -6 \\ 4 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 12 \\ 5 \end{bmatrix}$$

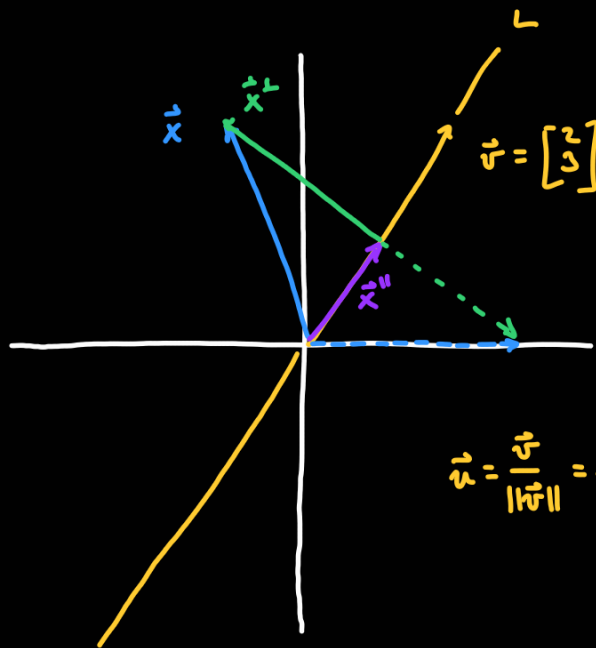
$$\vec{e}_2'' = \frac{3}{\sqrt{13}} \cdot \frac{1}{\sqrt{3}} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 6 \\ 9 \end{bmatrix}$$

$$\vec{e}_2^\perp = \begin{bmatrix} 0 \\ 1 \end{bmatrix} - \frac{1}{13} \begin{bmatrix} 6 \\ 9 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} -6 \\ 4 \end{bmatrix}$$

$$A = [T(\vec{e}_1) \quad T(\vec{e}_2)] = \frac{1}{13} \begin{bmatrix} -5 & -6 \\ 12 & 4 \end{bmatrix}$$

Want: basis \mathcal{B} of \mathbb{R}^2 such that the matrix of the reflection along $L = \text{span}(\vec{v})$ is

diagonal.



$$\vec{x} = \vec{x}'' + \vec{x}^\perp$$

$$T(\vec{x}) = \vec{x}'' - \vec{x}^\perp$$

If we can find a basis \mathcal{B}

of \mathbb{R}^2 such that \vec{u}_1 is

parallel to \vec{v} and \vec{u}_2 is

perpendicular to \vec{v} , then:

$$T(\vec{u}_1) = \vec{u}_1$$

$$T(\vec{u}_2) = -\vec{u}_2$$

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\sqrt{13}} \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad \vec{w} = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$

in L in L^\perp

Choose $\mathcal{B} = \{\vec{v}, \vec{w}\}$,

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

we find: $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$.

$$\left[[T(\vec{v})]_{\mathcal{B}} \quad [T(\vec{w})]_{\mathcal{B}} \right] = \left[\begin{bmatrix} 2 \\ 3 \end{bmatrix}_{\mathcal{B}} \quad \begin{bmatrix} -3 \\ 2 \end{bmatrix}_{\mathcal{B}} \right] = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\tau(\vec{w}) = -\vec{w} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$

Problem 3.4.65: Recall: A is similar to B if: $B = S^{-1} A S$ for S invertible matrix.

Prove that A an $n \times n$ matrix is similar to itself.

$$A = S^{-1} A S. \quad \text{Let } \underline{S = I_n}, \quad S^{-1} = I_n \quad \text{now } I_n \cdot A \cdot I_n = A.$$

$$\begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

Prove that if A is similar to B , then B is similar to A .

$$B = S^{-1} A S \quad \text{for } S \text{ some invertible matrix.}$$

want:
 $A = R^{-1} B R$ for some
 R invertible matrix.

Multiply by S on the LHS and by S^{-1} on the RHS:

$$S B S^{-1} = \underbrace{S}_{I_n} (\underbrace{S^{-1} A S}_{I_n}) S^{-1} = I_n A I_n = A$$

Rename $R = S^{-1}$, now $R^{-1} = (S^{-1})^{-1} = S$, so:

$$A = S B S^{-1} = R^{-1} B R \quad \text{with } R \text{ invertible matrix.}$$

So B is similar to A .

Problem 3.4.56: Find M such that $\begin{bmatrix} 1 \\ 2 \end{bmatrix}_M = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$, $\begin{bmatrix} 3 \\ 4 \end{bmatrix}_M = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$.

$$\begin{bmatrix} \vec{x} \end{bmatrix}_M = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \quad \text{means:} \quad \vec{x} = c_1 \cdot \vec{v}_1 + c_2 \cdot \vec{v}_2 = \underbrace{\begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ 1 & 1 \end{bmatrix}}_S \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = S \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}_M = \begin{bmatrix} 3 \\ 5 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 \\ 2 \end{bmatrix} = S \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 4 \end{bmatrix}_B = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \longrightarrow \begin{bmatrix} 3 \\ 4 \end{bmatrix} = S \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

One method: $S = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, and the equalities above give 4 equations.

We can solve this system.

Remember: $BA = B \begin{bmatrix} \vec{w}_1 & \dots & \vec{w}_m \end{bmatrix} = \begin{bmatrix} B\vec{w}_1 & \dots & B\vec{w}_m \end{bmatrix}$

$$\begin{aligned} S \begin{bmatrix} 3 \\ 5 \end{bmatrix} &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \\ S \begin{bmatrix} 2 \\ 3 \end{bmatrix} &= \begin{bmatrix} 3 \\ 4 \end{bmatrix} \end{aligned} \longrightarrow S \begin{bmatrix} 3 & 2 \\ 5 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \quad \text{so} \quad S = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 5 & 3 \end{bmatrix}^{-1}$$