

Recall: subspaces of \mathbb{R}^n

equation \longleftrightarrow span (linear combination)

$$x+y+z=0 \quad a \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \cdot \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \quad a, b \text{ real numbers}$$

plane in 3 dimensions

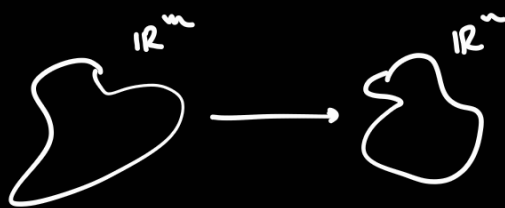
plane in 3 dimensions

Example: Consider the line given by:

$x+y+z=0$, find a matrix A with kernel this line.

$$\underbrace{2y+3z=0}$$

$$L = \left\{ t \cdot \begin{bmatrix} 1/2 \\ -3/2 \\ 1 \end{bmatrix} + \text{real number} \right\}$$



$m=3$

$n=2$

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}}_A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$a_{11}x + a_{12}y + a_{13}z = 0$$

$$a_{21}x + a_{22}y + a_{23}z = 0$$

equality giving $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ is in $\ker(A)$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 3 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x+2y+3z=0$$

✓ plane in 3 dimensions.

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \end{array} \right]$$

$$x = -2t - 3s$$

$$\begin{bmatrix} -2t - 3s \\ \dots \\ \dots \end{bmatrix}$$

$$\begin{matrix} \uparrow & \uparrow \\ \text{free} & \text{free} \\ t & s \end{matrix} \quad \begin{bmatrix} t \\ s \end{bmatrix} \quad t, s \text{ real numbers}$$

$$\begin{bmatrix} -2t-3s \\ t \\ s \end{bmatrix} = t \cdot \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + s \cdot \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

A augmented $\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 2 & 3 & 0 \end{array} \right] \xrightarrow{\frac{1}{2}R_2} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{3}{2} & 0 \end{array} \right] \xrightarrow{R_1 - R_2} \left[\begin{array}{ccc|c} 1 & 0 & \frac{-1}{2} & 0 \\ 0 & 1 & \frac{3}{2} & 0 \end{array} \right]$

\uparrow
free

Example: The matrix $\begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$ has image the line $\left\{ t \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} \mid t \text{ real} \right\}$

$a \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} + b \cdot \begin{bmatrix} 3 \\ 6 \end{bmatrix}$

Vectors $\vec{v}_1, \dots, \vec{v}_n$ are linearly independent if none of them can be obtained as a linear combination of the others.

$$\begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix}$$

$$\vec{v}_i = a_1 \vec{v}_1 + \dots + a_{i-1} \vec{v}_{i-1} + a_{i+1} \vec{v}_{i+1} + \dots + a_n \vec{v}_n$$

$$0 = a_1 \vec{v}_1 + \dots + a_{i-1} \vec{v}_{i-1} - \vec{v}_i + a_{i+1} \vec{v}_{i+1} + \dots + a_n \vec{v}_n$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow$

Some are non-zero

Vectors are linearly independent if when:

$$a_1 \vec{v}_1 + \dots + a_n \vec{v}_n = \vec{0} \quad \text{then} \quad a_1 = \dots = a_n = 0.$$

Suppose: $a_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + a_3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, then $\begin{matrix} a_1 + a_2 + a_3 = 0 \\ a_1 + a_2 = 0 \end{matrix}$.

This has one solution: $a_1=0, a_2=0, a_3=0$.

are these vectors linearly independent?

$$a_1=2 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + a_2=-1 \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + a_3=0 \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + a_4=1 \cdot \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

$$a_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + a_3 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + a_4 \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \iff \begin{bmatrix} 1 & 4 & 1 & 2 \\ 1 & 5 & 2 & 3 \\ 1 & 6 & 3 & 4 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Never the case. \rightarrow (i) No solution.

linear independence \rightarrow (ii) One solution. \otimes

linear dependence \rightarrow (iii) Infinite solutions.

ref \leftarrow

$$\left[\begin{array}{cccc|c} 1 & 4 & 1 & 2 & 0 \\ 1 & 5 & 2 & 3 & 0 \\ 1 & 6 & 3 & 4 & 0 \end{array} \right]$$

\otimes will be $a_1 = \dots = a_n = 0$.

$$2 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad 2 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

$$\left[\begin{array}{cccc|c} 1 & 4 & 1 & 2 & 0 \\ 1 & 5 & 2 & 3 & 0 \\ 1 & 6 & 3 & 4 & 0 \end{array} \right] \xrightarrow[R_3-R_1]{R_2-R_1} \left[\begin{array}{cccc|c} 1 & 4 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 2 & 2 & 2 & 0 \end{array} \right] \xrightarrow[R_3-2R_2]{R_1-4R_2} \left[\begin{array}{cccc|c} 1 & 0 & -3 & -2 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{bmatrix} 3a_3 + 2a_4 \\ -a_3 - a_4 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

$a_4=1$
 $a_3=0$

↑ free ↑ free

Basis: \forall a subspace of \mathbb{R}^n

A basis of V is a collection of vectors that span V and are

linearly independent.

Example: Give a basis for the image of $A = \begin{bmatrix} 1 & 4 & 1 & 2 \\ 1 & 5 & 2 & 3 \\ 1 & 6 & 3 & 4 \end{bmatrix}$.

Answer: $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$.

Answer: $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$.

Answer: $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$.

$$\text{im}(A) = \left\{ a \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + c \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + d \cdot \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \mid a, b, c, d \text{ real} \right\} \leftarrow \text{definition of span.}$$

definition of span. $\Rightarrow \text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right)$

$$\left[\begin{array}{cccc|c} 1 & 4 & 1 & 2 & 0 \\ 1 & 5 & 2 & 3 & 0 \\ 1 & 6 & 3 & 4 & 0 \end{array} \right] \xrightarrow{\text{ref}} \left[\begin{array}{cccc|c} 1 & 0 & -3 & -2 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \leftarrow \text{rank 2 } (\otimes)$$

rank 2 (\otimes) two vectors in the basis

free free \leftarrow remove them!

$$\text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right)$$

Given vectors $\vec{v}_1, \dots, \vec{v}_n$, their span is the set of all their linear combinations:

$$\text{span}(\vec{v}_1, \dots, \vec{v}_n) = \left\{ a_1 \vec{v}_1 + \dots + a_n \vec{v}_n \mid a_1, \dots, a_n \text{ any real numbers} \right\}$$

Image of $B = \begin{bmatrix} 2 & 4 & 1 & 1 \\ 3 & 5 & 2 & 1 \\ 4 & 6 & 3 & 1 \end{bmatrix}$.

$$\text{im}(B) = \text{span} \left(\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right)$$

not basis not basis

L line given by $\text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} \pi \\ \pi \\ \pi \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} \log 2 \\ \log 2 \\ \log 2 \end{bmatrix} \right)$

basis of L basis of L basis of L basis of L

$$4 \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

zero vector is never in a basis

$$a \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$L = \text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \right) \text{ is living in } \mathbb{R}^3.$$

not a basis

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

so $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is in $\text{span} \left(\begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \right)$

The span of the vectors $\vec{v}_1, \dots, \vec{v}_n$ is a subspace.

$\text{span}(\vec{v}_1, \dots, \vec{v}_n) \leftarrow$ subspace.

A basis is a collection of vectors $\vec{w}_1, \dots, \vec{w}_m$.

We can take the span of a basis: $\text{span}(\vec{w}_1, \dots, \vec{w}_m)$.

Vector space: \mathbb{R}^n .

The columns of A span $\text{im}(A)$.



The kernel of A tells you if the columns are a basis.

$$a_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + a_2 \cdot \begin{bmatrix} 4 \\ 5 \\ 2 \\ 6 \end{bmatrix} + a_3 \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix} + a_4 \cdot \begin{bmatrix} 2 \\ 3 \\ 4 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} 1 & 4 & 1 & 2 \\ 1 & 5 & 2 & 3 \\ 1 & 6 & 3 & 4 \end{bmatrix}}_A \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{ker}(A)$$

If $\text{ker}(A)$ has one vector, then the columns of A are linearly independent.

Finding whether some vectors are linearly independent is equivalent to

finding the kernel of the matrix having those vectors as columns.

Given a basis $\vec{v}_1, \dots, \vec{v}_n$, vectors in $\text{span}(\vec{v}_1, \dots, \vec{v}_n)$ can be written

in a unique way as a linear combination:

$$\vec{v} = c_1 \cdot \vec{v}_1 + \dots + c_n \vec{v}_n$$

unique.

We call c_1, \dots, c_n the coordinates of \vec{v} in terms of $\vec{v}_1, \dots, \vec{v}_n$.

V Kernel \longleftarrow subspaces \longrightarrow image W

$\vec{v}_1, \dots, \vec{v}_n$ \longleftarrow basis \longrightarrow $\vec{w}_1, \dots, \vec{w}_m$

$$V = \text{span}(\vec{v}_1, \dots, \vec{v}_n)$$

$$W = \text{span}(\vec{w}_1, \dots, \vec{w}_m)$$

Problem 2.1.14:

(b) $\begin{bmatrix} 2 & 3 \\ 5 & k \end{bmatrix}$, for which k does the matrix $\begin{bmatrix} 2 & 3 \\ 5 & k \end{bmatrix}^{-1}$ have integer entries?

$$\begin{bmatrix} 2 & 3 \\ 5 & k \end{bmatrix}^{-1} = \begin{bmatrix} k & -3 \\ -5 & 2 \end{bmatrix} \cdot \frac{1}{2k-15}$$

Long way: $\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \frac{1}{2k-15} \begin{bmatrix} k & -3 \\ -5 & 2 \end{bmatrix}$, this gives four equations in terms of the integers a, b, c, d . Solve for k .

Note:

$$\underbrace{-b-d}_{\text{both integers}} = \frac{3}{2k-15} - \frac{2}{2k-15} = \frac{1}{2k-15}$$

So $\frac{1}{2k-15} = n$ some integer.

$$\text{Ans: } \frac{1}{2k-15} = n \implies k = \frac{15}{2n} + 1 = 7.5 + \frac{1}{n}$$

$$(*) \quad nk = \frac{k}{2k-15}$$

$$\text{and: } \frac{k}{2k-15} = 7.5u + \frac{1}{2}$$

$$(*) \quad nk = 7.5u + \frac{1}{2}$$

is an integer.

So n should be odd. Then: $k = \frac{15}{2} + \frac{1}{2n}$ for n odd integer.

We found that if the entries are integers then k has this form.

We now check that if k has this form then the entries are

integers:

$$\begin{bmatrix} 2 & 3 \\ 5 & k \end{bmatrix}^{-1} = \frac{1}{2k-15} \begin{bmatrix} k & -3 \\ -5 & 2 \end{bmatrix} = \frac{1}{2\left(\frac{15}{2} + \frac{1}{2n}\right) - 15} \begin{bmatrix} \frac{15}{2} + \frac{1}{2n} & -3 \\ -5 & 2 \end{bmatrix} =$$

$$k = \frac{15}{2} + \frac{1}{2n}$$

$$= \frac{1}{15 + \frac{1}{n} - 15} \begin{bmatrix} \frac{15}{2} + \frac{1}{2n} & -3 \\ -5 & 2 \end{bmatrix} = n \cdot \begin{bmatrix} \frac{15}{2} + \frac{1}{2n} & -3 \\ -5 & 2 \end{bmatrix} =$$

$$= \begin{bmatrix} \frac{15n}{2} + \frac{1}{2} & -3n \\ -5n & 2n \end{bmatrix} = \begin{bmatrix} 7.5n + \frac{1}{2} & -3 \\ -5 & 2n \end{bmatrix}$$

Practice Midterm 1, Problem 6:

$$T: \mathbb{R}^3 \rightarrow \mathbb{R} \quad \vec{v} \text{ in } \mathbb{R}^3$$

$$\vec{x} \mapsto \vec{x} \cdot \vec{v} = T(\vec{x})$$

1. If $\vec{v} = \vec{0}$ then $T(\vec{x}) = \vec{x} \cdot \vec{0} = 0$ for all \vec{x} in \mathbb{R}^3 .

$$[1 \ 1 \ 0] \ [0 \ 1 \ 0]$$

$$\ker(\tau) = \mathbb{R}^3 \quad \text{basis } \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

$$\text{im}(\tau) = \{0\} \quad \text{basis } \{ \}.$$

2. If $\vec{v} \neq \vec{0}$ then $\text{im}(\tau) = \mathbb{R}$ with basis $\{[1]\}$.

$$\tau(\vec{v}) = \vec{v} \cdot \vec{v} \neq 0 \text{ in } \mathbb{R}.$$

$$\ker(\tau) = \{ \vec{x} \text{ in } \mathbb{R}^3 \mid \vec{x} \cdot \vec{v} = 0 \}, \quad \text{let } \vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \text{ then:}$$

$$0 = \vec{x} \cdot \vec{v} = v_1 x_1 + v_2 x_2 + v_3 x_3 \quad \leftarrow \text{plane with normal vector } \vec{v}.$$

2.1. If $v_1 = v_2 = 0$ then $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ are in $\ker(\tau)$, they are linearly independent, so they form a basis.

$$2.2. \text{ If } v_1 = 0 \text{ then } \begin{bmatrix} x_1 & 0 \\ x_2 & 1 \\ x_3 & \frac{-v_2}{v_3} \end{bmatrix} \text{ and } \begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ x_3 & \frac{-v_2}{v_3} \end{bmatrix} \text{ are in } \ker(\tau),$$

$$0 = 0 \cdot 0 + v_2 \cdot 1 + v_3 \cdot x_3$$

$$0 = 0 \cdot 1 + v_2 \cdot 1 + v_3 \cdot x_3$$

$$\frac{-v_2}{v_3} = x_3$$

$$\frac{-v_2}{v_3} = x_3$$

and they are linearly independent, so they form a basis.

$$2.3. \text{ If } v_1, v_2, v_3 \text{ are all non-zero then } \begin{bmatrix} -\frac{v_2}{v_3} \\ \frac{v_2}{v_3} \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{v_3}{v_1} \\ 0 \\ 1 \\ 1 \end{bmatrix} \text{ work.}$$

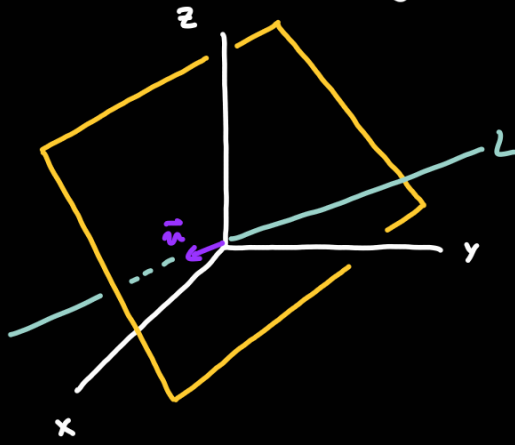
$$0 = v_1 \cdot x_1 + v_2 \cdot 1 + v_3 \cdot 0$$

$$0 = v_1 \cdot x_1 + v_2 \cdot 0 + v_3 \cdot 1$$

$$x_1 = \frac{-v_2}{v_1}$$

$$x_1 = \frac{-v_3}{v_1}$$

The matrix associated to T is given by: $\left[T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) \quad T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) \quad T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) \right]$.



$$\underbrace{y=z}_{\checkmark} \quad y-z=0 \quad \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \text{ gives } L$$

vector perpendicular to \checkmark

$$\text{ref}_{\checkmark}(\vec{x}) = \text{proj}_{\checkmark}(\vec{x}) - \text{proj}_L(\vec{x})$$

$$\text{proj}_L(\vec{x}) = (\vec{x} \cdot \vec{u}) \cdot \vec{u}$$

$$\vec{u} = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

$$\text{proj}_{\checkmark}(\vec{x}) = \vec{x} - \text{proj}_L(\vec{x})$$

$$\begin{aligned} T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} - \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \\ &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} - \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} - \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \\ &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) &= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} - \left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}\right) \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \\ &= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

