

Recall: We claimed that there was a basis \mathcal{B} such that the linear transformations had a diagonal matrix associated to them.

$$(1) A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \quad (2) A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \quad (3) A = \begin{bmatrix} 2/3 & 1/3 & -1/3 \\ 1/3 & 2/3 & 1/3 \\ -1/3 & 1/3 & 2/3 \end{bmatrix}$$

Find one basis for each linear transformation (satisfying the above).

$$(1) \mathcal{S} = \{ \vec{e}_1, \vec{e}_2 \} \quad \mathcal{B} = \left[\begin{array}{c} [A \begin{bmatrix} 1 \\ 0 \end{bmatrix}]_{\mathcal{S}} \\ [A \begin{bmatrix} 0 \\ 1 \end{bmatrix}]_{\mathcal{S}} \end{array} \right] = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

↑
eigenvectors of $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$

$$(2) \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} \quad \mathcal{B} = \left[\begin{array}{c} [A \begin{bmatrix} 1 \\ 1 \end{bmatrix}]_{\mathcal{B}} \\ [A \begin{bmatrix} -1 \\ 1 \end{bmatrix}]_{\mathcal{B}} \end{array} \right] = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

↑
eigenvectors of $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

$$(3) \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix} \right\} \quad \mathcal{B} = \left[\begin{array}{c} [A \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}]_{\mathcal{B}} \\ [A \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}]_{\mathcal{B}} \\ [A \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}]_{\mathcal{B}} \end{array} \right] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

↑
eigenvectors of $\frac{1}{3} \begin{bmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 2 \end{bmatrix}$

Given A a matrix, a non-zero vector \vec{v} is called an eigenvector if there is a scalar

λ in A such that $A\vec{v} = \lambda\vec{v}$. We say that λ is the eigenvalue associated to the eigenvector \vec{v} .

(1) $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ has eigenvectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ with associated eigenvalues 1, 2 respectively.

(2) $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ has eigenvectors $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ with eigenvalues 2, 0 respectively.

(3) $A = \frac{1}{3} \begin{bmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 2 \end{bmatrix}$ has eigenvectors $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}$ with eigenvalues 1, 1, 0 respectively.

Question: What are the possible eigenvalues of an orthogonal matrix? Q

If \vec{v} is an eigenvector of eigenvalue λ , then:

$$Q\vec{v} = \lambda\vec{v} \quad \|Q\vec{v}\| = \|\vec{v}\|$$

$$\underbrace{\|\vec{v}\|}_{\vec{v} \neq \vec{0}} = \|Q\vec{v}\| = \|\lambda\vec{v}\| = |\lambda| \cdot \underbrace{\|\vec{v}\|}_{\vec{v} \neq \vec{0}} \quad \text{so } 1 = |\lambda| \quad \text{so } \lambda = \pm 1.$$

① Given A an $n \times n$ matrix with eigenvectors $\vec{v}_1, \dots, \vec{v}_n$. If $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$ form a basis of \mathbb{R}^n then:

a basis of \mathbb{R}^n then:

$$\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} = \begin{bmatrix} | & & | \\ \frac{1}{\vec{v}_1} & \dots & \frac{1}{\vec{v}_n} \\ | & & | \end{bmatrix}^{-1} \cdot A \cdot \begin{bmatrix} | & & | \\ \frac{1}{\vec{v}_1} & \dots & \frac{1}{\vec{v}_n} \\ | & & | \end{bmatrix}.$$

If we understand (enough) eigenvectors, we understand the matrix.

② Given A an $n \times n$ matrix such that:

$$\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} = \begin{bmatrix} | & & | \\ \frac{1}{\vec{v}_1} & \dots & \frac{1}{\vec{v}_n} \\ | & & | \end{bmatrix}^{-1} \cdot A \cdot \begin{bmatrix} | & & | \\ \frac{1}{\vec{v}_1} & \dots & \frac{1}{\vec{v}_n} \\ | & & | \end{bmatrix}$$

If we understand the matrix then we understand the eigenvectors.

where $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis of \mathbb{R}^n . Then $\vec{v}_1, \dots, \vec{v}_n$ are eigenvectors of A with eigenvalues $\lambda_1, \dots, \lambda_n$ respectively.

$$\begin{array}{c} \text{eigenvalue} \\ \swarrow \\ A\vec{v} = \lambda\vec{v} \\ \uparrow \\ \text{eigenvector} \end{array} \quad A\vec{v} - \lambda\vec{v} = 0 \quad (A - \lambda \cdot I_n) \cdot \vec{v} = 0 \quad (\vec{v} \text{ in } \ker(A - \lambda \cdot I_n)).$$

If $\det(A - \lambda \cdot I_n) \neq 0$ there are no solutions. So we need $\det(A - \lambda \cdot I_n) = 0$.

The characteristic equation of A is: $\det(A - \lambda \cdot I_n) = 0$.

The characteristic polynomial of A is: $f_A(x) = \det(A - x \cdot I_n)$.

A real number λ is an eigenvalue of A if and only if $f_A(\lambda) = 0$.

Example: Find (by factoring the characteristic polynomial) the eigenvalues of:

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\begin{aligned} f_A(x) &= \det\left(\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} - x \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = \det \begin{bmatrix} 1-x & 1 \\ 1 & 1-x \end{bmatrix} = (1-x)^2 - 1 = \\ &= 1 + x^2 - 2x - 1 = x^2 - 2x = x \cdot (x-2) \end{aligned}$$

Example: Find $f_A(x)$ for $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

$$\begin{aligned} f_A(x) &= \det \begin{bmatrix} a-x & b \\ c & d-x \end{bmatrix} = (a-x)(d-x) - bc = x^2 - dx - ax + ad - bc = \\ &= x^2 - \underbrace{(a+d)}_{\substack{\text{sum of} \\ \text{diagonal} \\ \text{elements}}} x + \underbrace{(ad-bc)}_{\det(A)} \end{aligned}$$

The sum of the diagonal elements of a matrix A is called the trace of A ,

denoted $\text{tr}(A)$.

Given a matrix A and an eigenvalue λ , the algebraic multiplicity of λ is the

largest integer k such that: $f_A(x) = (x-\lambda)^k \cdot g(x)$ with $g(\lambda) \neq 0$.

Example: Find the algebraic multiplicities of the eigenvalues of $\begin{bmatrix} 2/3 & 1/3 & -1/3 \\ 1/3 & 2/3 & 1/3 \\ -1/3 & 1/3 & 2/3 \end{bmatrix}$.

$$f_A(x) = \det \begin{bmatrix} \frac{2}{3}-x & \frac{1}{3} & -\frac{1}{3} \\ \frac{1}{3} & \frac{2}{3}-x & \frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & \frac{2}{3}-x \end{bmatrix} = \dots = -x^3 + 2x^2 - x = -x^0 \cdot (x-1)^2.$$

?
0

?
1

A has eigenvalues $0, 1$ with multiplicities $1, 2$.

Question: Let A be $n \times n$. How many distinct eigenvalues can A have?

$f_A(x)$ is a polynomial of degree n , so it has at most n solutions.
 (eigenvalues)

So A has at most n distinct eigenvalues.

Example: $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ $f_A(x) = \det \begin{bmatrix} x & -1 \\ 1 & x \end{bmatrix} = x^2 + 1.$

no solutions

Example: Let A be a matrix of odd size. Does it have eigenvalue(s)?

$n \times n$ n odd

