Differential Geometry I - Homework 1

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We consider S^n with the smooth structure given by the stereographic projections P_N and P_S (*N* being the north pole and *S* the south pole). In particular, the problem implicitly tells us that the stereographic projections are \mathcal{C}^{∞} related. We want to show that the following charts are \mathcal{C}^{∞} related to the stereographic projections:

$$f : S^{n} \cap \{x \in \mathbb{R}^{n+1} : x^{i} > 0\} \longrightarrow \mathbb{R}^{n}$$
$$(x_{1}, \dots, x_{n+1}) \longmapsto (x_{1}, \dots, x_{i-1}, x_{i+1}, \dots, x_{n+1}),$$
$$g : S^{n} \cap \{x \in \mathbb{R}^{n+1} : x^{i} < 0\} \longrightarrow \mathbb{R}^{n}$$
$$(x_{1}, \dots, x_{n+1}) \longmapsto (x_{1}, \dots, x_{i-1}, x_{i+1}, \dots, x_{n+1}).$$

In virtue of the above, it is enough to prove that f_i is related to P_S and g_i is related to P_N . To do this, we find an explicit expression for the stereographic projections, their inverses and the inverses of the two functions above.

Starting with P_N , we consider the vector joining the north pole N with (x_1, \ldots, x_{n+1}) a generic point in $S^n \setminus \{N\}$, that is, $\vec{v} = (x_1, \ldots, x_n, x_{n+1} - 1)$. Now we add this to the north pole enough times so that we land in the plane $x_{n+1} = 0$, that is, we want $k \in \mathbb{R}$ such that $1 + k(x_{n+1} - 1) = 0$, otherwise said $k = 1/1 - x_{n+1}$. Hence:

$$P_N : S^n \setminus \{N\} \longrightarrow \mathbb{R}^n$$

$$(x_1, \dots, x_{n+1}) \longmapsto \left(\frac{x_1}{1 - x_{n+1}}, \dots, \frac{x_n}{1 - x_{n+1}}\right)$$

To find the inverse P_N^{-1} , we let $(X_1, \ldots, X_n) \in \mathbb{R}^n$ and $(x_1, \ldots, x_{n+1}) \in S^n \setminus \{N\}$ be our coordinates and we have to consider the system of equations given by:

$$X_1 = \frac{x_1}{1 - x_{n+1}}, \dots, X_n = \frac{x_n}{1 - x_{n+1}}, x_1^2 + \dots + x_{n+1}^2 = 1,$$

that is:

$$x_1 = X_1(1 - x_{n+1}), \dots, x_n = X_n(1 - x_{n+1}), (X_1(1 - x_{n+1}))^2 + \dots + (X_n(1 - x_{n+1}))^2 + x_{n+1}^2 = 1$$

hence there are two solutions for x_{n+1} :

$$x_{n+1} = -1$$
 and thus $x_1 = \dots = x_n = 0$ or $x_{n+1} = \frac{X_1^2 + \dots + X_n^2 - 1}{X_1^2 + \dots + X_n^2 + 1}$,

resulting in:

$$P_N^{-1} : \mathbb{R}^n \longrightarrow S^n \setminus \{N\}$$

$$(X_1, \dots, X_n) \longmapsto \left(\frac{2X_1}{X_1^2 + \dots + X_n^2 + 1}, \dots, \frac{2X_n}{X_1^2 + \dots + X_n^2 + 1}, \frac{X_1^2 + \dots + X_n^2 - 1}{X_1^2 + \dots + X_n^2 + 1}\right).$$

Notice how component wise, the function is \mathcal{C}^{∞} .

Continuing with P_S , we consider the vector joining the south pole S with (x_1, \ldots, x_{n+1}) a generic point in $S^n \setminus \{S\}$, that is, $\vec{v} = (x_1, \ldots, x_n, x_{n+1} + 1)$. Now we add this to the north pole enough times so that we land in the plane $x_{n+1} = 0$, that is, we want $k \in \mathbb{R}$ such that $-1 + k(x_{n+1} + 1) = 0$, otherwise said $k = 1/1 + x_{n+1}$. Hence:

$$P_S : S^n \setminus \{S\} \longrightarrow \mathbb{R}^n$$
$$(x_1, \dots, x_{n+1}) \longmapsto \left(\frac{x_1}{1 + x_{n+1}}, \dots, \frac{x_n}{1 + x_{n+1}}\right).$$

To find the inverse P_S^{-1} , we let $(X_1, \ldots, X_n) \in \mathbb{R}^n$ and $(x_1, \ldots, x_{n+1}) \in S^n \setminus \{N\}$ be our coordinates and we have to consider the system of equations given by:

$$X_1 = \frac{x_1}{1 + x_{n+1}}, \dots, X_n = \frac{x_n}{1 + x_{n+1}}, x_1^2 + \dots + x_{n+1}^2 = 1,$$

that is:

$$x_1 = X_1(1+x_{n+1}), \dots, x_n = X_n(1+x_{n+1}), (X_1(1+x_{n+1}))^2 + \dots + (X_n(1+x_{n+1}))^2 + x_{n+1}^2 = 1$$

hence there are two solutions for x_{n+1} :

$$x_{n+1} = 1$$
 and thus $x_1 = \dots = x_n = 0$ or $x_{n+1} = -\frac{X_1^2 + \dots + X_n^2 - 1}{X_1^2 + \dots + X_n^2 + 1}$,

resulting in:

$$P_{S}^{-1} : \mathbb{R}^{n} \longrightarrow S^{n} \setminus \{S\}$$

$$(X_{1}, \dots, X_{n}) \longmapsto \left(\frac{2X_{1}}{X_{1}^{2} + \dots + X_{n}^{2} + 1}, \dots, \frac{2X_{n}}{X_{1}^{2} + \dots + X_{n}^{2} + 1}, -\frac{X_{1}^{2} + \dots + X_{n}^{2} - 1}{X_{1}^{2} + \dots + X_{n}^{2} + 1}\right)$$

Notice how component wise, the function is \mathcal{C}^{∞} .

Finally, a computation of the inverses f_j^{-1} and g_j^{-1} is obtained from imposing that the norm of the coordinates is one, hence all the components are the identity except the *j*-th one (note how \hat{X}_j denotes that there is no X_j component in \mathbb{R}^n):

Again, notice how in the square root the term X_j^2 is not included in the subtraction. Moreover, notice how component wise in their domain, the functions are \mathcal{C}^{∞} . It is important to mention that we need here to restrict to the domain, since the assignment $(X_1, \ldots, \hat{X}_j, \ldots, X_n) \mapsto \sqrt{1 - X_1^2 - \cdots - X_n^2}$ is not \mathcal{C}^{∞} in general: if $1 = X_1^2 + \cdots + X_n^2$ this is not continuously differentiable. However, since we must land in $S^n \cap \{x \in \mathbb{R}^{n+1} : x^i > 0\}$ or $S^n \cap \{x \in \mathbb{R}^{n+1} : x^i < 0\}$, we have that $X_1^2 + \cdots + X_n^2 > 0$, resolving this issue.

Now we have that all the compositions $f_j \circ P_S^{-1}$, $g_j \circ P_N^{-1}$, $P_S \circ f_j^{-1}$ and $P_N \circ g_j^{-1}$ are component wise \mathcal{C}^{∞} since over the real numbers the composition of \mathcal{C}^{∞} functions is \mathcal{C}^{∞} , as desired. We will have to restrict us to the case of \mathcal{C}^{∞} functions over the reals multiple times in the following.

1. Prove that all \mathcal{C}^{∞} functions are continuous, and that the composition of \mathcal{C}^{∞} functions is \mathcal{C}^{∞} .

For the first part, given $f: M \longrightarrow N \ a \ C^{\infty}$ function between manifolds, we want to check that it is continuous. Let $V \subset N$ be an open set. Since we have a maximal atlas in N that gives the notion of smoothness, and the charts in such atlas cover N and are compatible, we can find a homeomorphism y such that (y, V) belongs to the atlas in N. Now, we know that by definition, for any chart (x, U) of M we have that $y \circ f \circ x^{-1} : x(U) \longrightarrow y(V)$ is a real valued C^{∞} function, hence it is continuous. Moreover, since x and y are diffeomorphisms in their respective smooth structures, they are homeomorphisms hence continuous with continuous inverse. Since the composition of continuous functions between topological spaces are continuous, we obtain that $f = y^{-1} \circ (y \circ f \circ x^{-1}) \circ x : f^{-1}(V) \longrightarrow V$ is a continuous function. In particular, for every $V \subset N$ open, we have that $f^{-1}(V)$ is open, which is the definition of $f: M \longrightarrow N$ being continuous, as desired.

For the second part, let $f: M \longrightarrow N$ and $g: N \longrightarrow T$ be \mathcal{C}^{∞} functions. Let (x, U), (y, V), (z, W) be any charts in M, N, T respectively. Then:

$$x \circ (g \circ f) \circ z^{-1} = (x \circ g \circ y^{-1}) \circ (y \circ g \circ z^{-1}) : z(W) \longrightarrow y(V) \longrightarrow x(U),$$

which is a \mathcal{C}^{∞} function in the real numbers since is a composition of two \mathcal{C}^{∞} functions in the real numbers, in virtue of the definition of f and g being \mathcal{C}^{∞} functions between manifolds. Hence, this means precisely that $g \circ f : M \longrightarrow T$ is a \mathcal{C}^{∞} function between manifolds, as desired.

2. Prove that a function $f: M \longrightarrow N$ is \mathcal{C}^{∞} if and only if $g \circ f: M \longrightarrow \mathbb{R}$ is \mathcal{C}^{∞} for every $g: N \longrightarrow \mathbb{R}$ that is \mathcal{C}^{∞} .

 \Rightarrow) Let $f: M \longrightarrow N$ and $g: N \longrightarrow \mathbb{R}$ be \mathcal{C}^{∞} functions. By the above, we know that the composition of \mathcal{C}^{∞} functions is a \mathcal{C}^{∞} function, hence $g \circ f: M \longrightarrow \mathbb{R}$ is a \mathcal{C}^{∞} function.

 \Leftarrow) Let x, U, (y, V) be any charts on M, N respectively. Denoting by $y_i : N \longrightarrow \mathbb{R}$ the *i*-th component of y, we obtain by hypothesis that $y_i \circ f : M \longrightarrow \mathbb{R}$ is a \mathcal{C}^{∞} function. Moreover, since x^{-1} is a \mathcal{C}^{∞} function because x being a chart in particular means that it is a diffeomorphism, by the point above we obtain that $y_i \circ f \circ x^{-1} : x(U) \longrightarrow y_i(V)$ is a real valued \mathcal{C}^{∞} function. Hence the function $y \circ f \circ x^{-1} : x(U) \longrightarrow y(V)$ is real valued and \mathcal{C}^{∞} component wise, meaning that it is \mathcal{C}^{∞} as a real valued function. This is precisely the definition of $f : M \longrightarrow N$ being a \mathcal{C}^{∞} function between manifolds.

Let a function $f : \mathbb{H}^n \longrightarrow \mathbb{R}$ have two \mathcal{C}^{∞} extensions g and h defined on a neighborhood of \mathbb{H}^n . Prove that $\partial_j g$ coincides with $\partial_j h$ on $\mathbb{R}^{n-1} \times \{0\}$.

First, recall that g and h being extensions of f means that $g(\mathbb{H}^n) = f(\mathbb{H}^n) = h(\mathbb{H}^n)$. Now, applying the definition of a partial derivative for $1 \le j \le n-1$, we obtain that:

$$\partial_j g(x_1, \dots, x_{n-1}, 0) = \lim_{x \to 0} \frac{g(x_1, \dots, x_j + x, \dots, x_{n-1}, 0) - g(x_1, \dots, x_{n-1}, 0)}{x}$$

=
$$\lim_{x \to 0} \frac{f(x_1, \dots, x_j + x, \dots, x_{n-1}, 0) - f(x_1, \dots, x_{n-1}, 0)}{x}$$

=
$$\lim_{x \to 0} \frac{h(x_1, \dots, x_j + x, \dots, x_{n-1}, 0) - h(x_1, \dots, x_{n-1}, 0)}{x}$$

=
$$\partial_j h(x_1, \dots, x_{n-1}, 0),$$

since both $(x_1, \ldots, x_j + x, \ldots, x_{n-1}, 0), (x_1, \ldots, x_{n-1}, 0) \in \mathbb{H}^n$. Notice that for the last component, since we assume that g and h are \mathcal{C}^{∞} , the limit that we want to compute is well defined, hence it doesn't matter how we make $x \in \mathbb{R}$ go to 0 because all of the ways will coincide. Hence we can apply the above for the case x > 0, j = n and obtain:

$$\partial_n g(x_1, \dots, x_{n-1}, 0) = \lim_{x \to 0} \frac{g(x_1, \dots, x_{n-1}, x) - g(x_1, \dots, x_{n-1}, 0)}{x}$$
$$= \lim_{x \to 0} \frac{f(x_1, \dots, x_{n-1}, x) - f(x_1, \dots, x_{n-1}, 0)}{x}$$
$$= \lim_{x \to 0} \frac{h(x_1, \dots, x_{n-1}, x) - h(x_1, \dots, x_{n-1}, 0)}{x}$$
$$= \partial_n h(x_1, \dots, x_{n-1}, 0),$$

since again $(x_1, \ldots, x_{n-1}, x), (x_1, \ldots, x_{n-1}, 0) \in \mathbb{H}^n$ because of the choice for x. This proves the desired result.

Consider two smooth structures over \mathbb{R} , the first \mathcal{U} being the maximal atlas containing the identity and the second \mathcal{V} the maximal atlas containing taking the third power.

1. Show that the homeomorphisms ϕ_0 and ϕ_1 are not \mathcal{C}^{∞} related. For this, note that $\phi_1^{-1}(x) = \sqrt[3]{x}$, hence:

$$\begin{array}{ccccc} \phi_0 \circ \phi_1^{-1} & : & \mathbb{R} & \longrightarrow & \mathbb{R} \\ & & x & \longmapsto & \sqrt[3]{x} \end{array} \quad \text{with} \quad \begin{array}{ccccc} (\phi_0 \circ \phi_1^{-1})' & : & \mathbb{R} & \longrightarrow & \mathbb{R} \\ & & x & \longmapsto & \frac{1}{2\sqrt[3]{x^2}} \end{array}$$

is a function that is not \mathcal{C}^{∞} (it is not even \mathcal{C}^1 , the derivative is not continuous), hence ϕ_0 and ϕ_1 are not \mathcal{C}^{∞} related.

2. Equip $M = \mathbb{R}$ with \mathcal{U} and $N = \mathbb{R}$ with \mathcal{V} , consider:

we want to find which of these maps is smooth. Notice that g is not smooth since for the defining charts ϕ_0 of \mathcal{U} and ϕ_1 of \mathcal{V} we have:

$$\begin{array}{cccc} \phi_0 \circ g \circ \phi_1^{-1} & : & \mathbb{R} & \longrightarrow & \mathbb{R} \\ & & x & \longmapsto & \sqrt[3]{x} \end{array}$$

which, as stated above, is not \mathcal{C}^{∞} . For f, we can apply the same charts and find that:

$$\begin{array}{rccc} \phi_1 \circ f \circ \phi_0^{-1} & : & \mathbb{R} & \longrightarrow & \mathbb{R} \\ & & x & \longmapsto & x \end{array}$$

which is indeed \mathcal{C}^{∞} . Now consider any charts x in M and y in N. Their defining property is that they are \mathcal{C}^{∞} related to ϕ_0 and ϕ_1 respectively, in particular, $\phi_0 \circ x^{-1}$ is \mathcal{C}^{∞} and $y \circ \phi_1^{-1}$ is \mathcal{C}^{∞} . Now:

$$y \circ f \circ x^{-1} = (y \circ \phi_1^{-1}) \circ (\phi_1 \circ f \circ \phi_0^{-1}) \circ (\phi_0 \circ x^{-1})$$

is a real valued \mathcal{C}^{∞} function since it is the composition of three real valued \mathcal{C}^{∞} functions. Since we proved this for any charts, this is precisely the definition of $f: M \longrightarrow N$ being \mathcal{C}^{∞} between manifolds.

3. Show that a function $h: N \longrightarrow \mathbb{R}$ is smooth at x = 0 if and only if the Taylor series of h at 0 contains only terms of the form x^{3k} with $k \in \mathbb{N}$.

 \Rightarrow) Let $h: N \longrightarrow \mathbb{R}$ be smooth at x = 0. This in particular means that:

$$\begin{array}{rccc} \phi_0 \circ h \circ \phi_1^{-1} & : & \mathbb{R} & \longrightarrow & \mathbb{R} \\ & & x & \longmapsto & h\left(\sqrt[3]{x}\right) \end{array}$$

is smooth. Since $h : \mathbb{R} \longrightarrow \mathbb{R}$, we have the usual form for its Taylor series:

$$h(x) = \sum_{n=0}^{\infty} \frac{h^{(n)}(0)}{n!} x^n \text{ hence } h\left(\sqrt[3]{x}\right) = \sum_{n=0}^{\infty} \frac{h^{(n)}(0)}{n!} \sqrt[3]{x^n}.$$

Notice that since this is a Taylor series, it converges at x = 0 and thus we may find the derivative at x = 0 by differentiating inside the sum. However checking element wise, $\sqrt[3]{x^n}$ is \mathcal{C}^{∞} when n = 3k for $k \in \mathbb{N}$, but in the rest of the cases we find that $\sqrt[3]{x^n}$ differentiated $n \mod 3$ times is no longer \mathcal{C}^1 , hence $\sqrt[3]{x^n}$ is not \mathcal{C}^{∞} . Thus, for h to be smooth, we need to only have the terms of the form x^{3k} for $k \in \mathbb{N}$ in the Taylor expansion.

 \Leftarrow) Suppose $h: N \longrightarrow \mathbb{R}$ has as a Taylor expansion near x = 0:

$$h(x) = \sum_{n=0}^{\infty} h_n x^{3n}.$$

Then near x = 0 we have:

$$\phi_0 \circ h \circ \phi_1^{-1}(x) = h\left(\sqrt[3]{x}\right) = \sum_{n=0}^{\infty} h_n x^n.$$

This allow us to well define $(\phi_0 \circ h \circ \phi_1^{-1})^{(n)}(0) = n!h_n$ for $n \in \mathbb{N}$. Hence $\phi_0 \circ h \circ \phi_1^{-1}$ has derivatives of all orders at x = 0, that is, it is smooth at x = 0.